

## Ratings and Specifications

Time Rating: Continuous  
 Vibration Class: V15  
 Insulation Resistance: 500 VDC, 10 M $\Omega$  min.  
 Ambient Temperature: 0 to 40°C  
 Excitation: Permanent magnet  
 Mounting: Flange-mounted  
 Thermal Class: F

Withstand Voltage: 1500 VAC for one minute (200-V class)  
 1800 VAC for one minute (400-V class)

Enclosure: Totally enclosed, self-cooled, IP67  
 (except for shaft opening)

Note: IP22 for SGMSV-70 servomotors.

Ambient Humidity: 20% to 80% (no condensation)

Drive Method: Direct drive

Rotation Direction: Counterclockwise (CCW) with forward run reference  
 when viewed from the load side

### 200-V Class

Servomotor Model: SGMSV-□□□□		10A	15A	20A	25A	30A	40A	50A	70A
Rated Output*	kW	1.0	1.5	2.0	2.5	3.0	4.0	5.0	7.0
Rated Torque*	N·m	3.18	4.90	6.36	7.96	9.80	12.6	15.8	22.3
Instantaneous Peak Torque*	N·m	9.54	14.7	19.1	23.9	29.4	37.8	47.6	54
Rated Current*	A <sub>rms</sub>	5.7	9.3	12.1	13.8	17.9	25.4	27.6	38.3
Instantaneous Max. Current*	A <sub>rms</sub>	17	28	42	44.5	56	77	84	105
Rated Speed*	min <sup>-1</sup>	3000							
Max. Speed*	min <sup>-1</sup>	6000	5000						
Torque Constant	N·m/A <sub>rms</sub>	0.636	0.590	0.561	0.610	0.582	0.519	0.604	0.604
Rotor Moment of Inertia	×10 <sup>-4</sup> kg·m <sup>2</sup>	1.74 (1.99)	2.00 (2.25)	2.47 (2.72)	3.19 (3.44)	7.00 (9.2)	9.60 (11.8)	12.3 (14.5)	12.3
Rated Power Rate*	kW/s	58 (51)	120 (107)	164 (149)	199 (184)	137 (104)	165 (135)	203 (172)	404
Rated Angular Acceleration*	rad/s <sup>2</sup>	18300 (16000)	24500 (21800)	25700 (23400)	25000 (23100)	14000 (10700)	13100 (10700)	12800 (10900)	18100
Applicable SERVOPACK	SGDV-□□□□	7R6A	120A	180A	200A	200A	330A	330A	550A

\*: These items and torque-motor speed characteristics quoted in combination with a SERVOPACK are at an armature winding temperature of 20°C.

Notes: 1 The values in parentheses are for servomotors with holding brakes.

2 The above specifications show the values under the cooling condition when the following heat sinks are mounted on the servomotors.

SGMSV-10A/-15A/-20A/-25A : 300 mm×300 mm×12 mm (aluminum)

SGMSV-30A/-40A/-50A/-70A : 400 mm×400 mm×20 mm (aluminum)

### 400-V Class

Servomotor Model: SGMSV-□□□□		10D	15D	20D	25D	30D	40D	50D
Rated Output*	kW	1.0	1.5	2.0	2.5	3.0	4.0	5.0
Rated Torque*	N·m	3.18	4.9	6.36	7.96	9.8	12.6	15.8
Instantaneous Peak Torque*	N·m	9.54	14.7	19.1	23.9	29.4	37.8	47.6
Rated Current*	A <sub>rms</sub>	2.8	4.7	6.1	7.4	8.9	12.5	13.8
Instantaneous Max. Current*	A <sub>rms</sub>	8.5	14	20	25	28	38	42
Rated Speed*	min <sup>-1</sup>	3000						
Max. Speed*	min <sup>-1</sup>	6000	5000					
Torque Constant	N·m/A <sub>rms</sub>	1.27	1.23	1.18	1.15	1.16	1.06	1.21
Rotor Moment of Inertia	×10 <sup>-4</sup> kg·m <sup>2</sup>	1.74 (1.99)	2.00 (2.25)	2.47 (2.72)	3.19 (3.44)	7.00 (9.2)	9.60 (11.8)	12.3 (14.5)
Rated Power Rate*	kW/s	58 (51)	120 (107)	164 (149)	199 (184)	137 (104)	165 (135)	203 (172)
Rated Angular Acceleration*	rad/s <sup>2</sup>	18300 (16000)	24500 (21800)	25700 (23400)	25000 (23100)	14000 (10700)	13100 (10700)	12800 (10900)
Applicable SERVOPACK	SGDV-□□□□	3R5D	5R4D	8R4D	120D	120D	170D	170D

\*: These items and torque-motor speed characteristics quoted in combination with a SERVOPACK are at an armature winding temperature of 20°C.

Notes: 1 The values in parentheses are for servomotors with holding brakes.

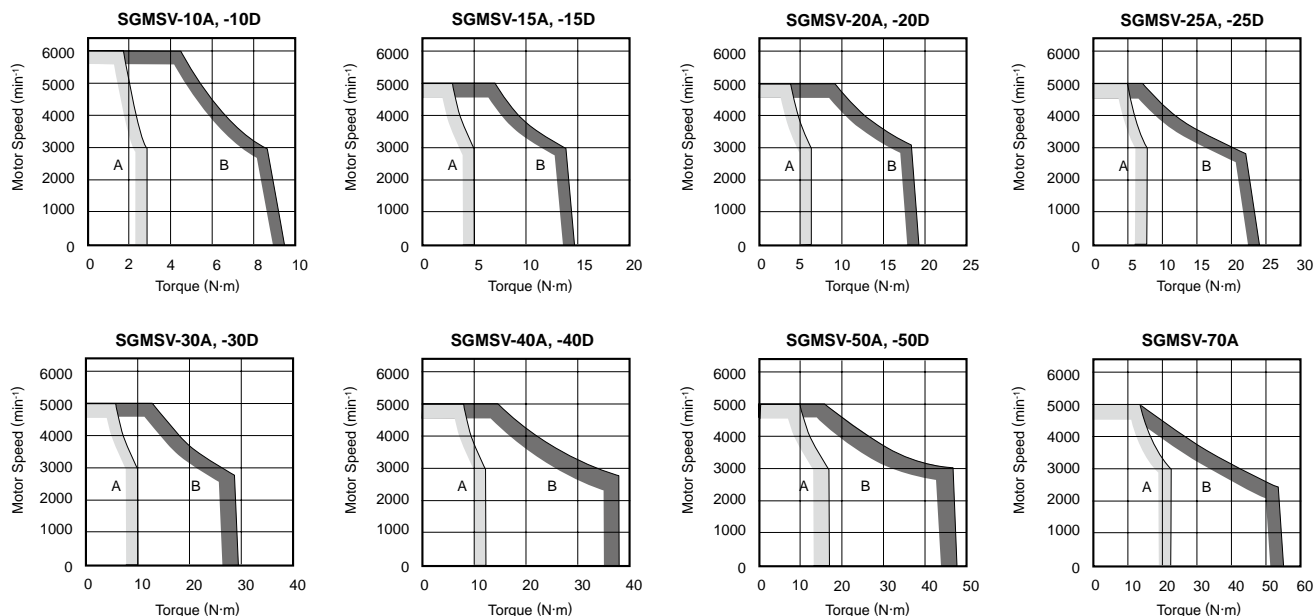
2 The above specifications show the values under the cooling condition when the following heat sinks are mounted on the servomotors.

SGMSV-10D/-15D/-20D/-25D : 300 mm×300 mm×12 mm (aluminum)

SGMSV-30D/-40D/-50D : 400 mm×400 mm×20 mm (aluminum)

**Ratings and Specifications**

● Torque-Motor Speed Characteristics(200 V/400 V) **A**: Continuous Duty Zone **B**: Intermittent Duty Zone (Note1)



Note: 1 When the effective torque during intermittent duty is within the rated torque, the servomotor can be used within the intermittent duty zone.  
 2 When the main circuit cable length exceeds 20 m, note that the intermittent duty zone of the Torque-Motor Speed Characteristics will shrink as the line-to-line voltage drops.

● Holding Brake Electrical Specifications

Servomotor Model	Servomotor Rated Output kW	Holding Brake Specifications				
		Holding Torque N·m	Rated Voltage 24 VDC		Rated Voltage 90 VDC	
			Capacity W	Rated Current A (at 20°C)	Capacity W	Rated Current A (at 20°C)
SGMSV-10	1.0	7.84	12	0.5	12	0.13
SGMSV-15	1.5	7.84	12	0.5	12	0.13
SGMSV-20	2.0	7.84	12	0.5	12	0.13
SGMSV-25	2.5	10	12	0.5	12	0.13
SGMSV-30	3.0	20	10	0.41	10	0.11
SGMSV-40	4.0	20	10	0.41	10	0.11
SGMSV-50	5.0	20	10	0.41	10	0.11

Notes: 1 The holding brake is only used to hold the load and cannot be used to stop the servomotor.  
 2 The holding brake open time and holding brake operation time vary depending on which discharge circuit is used. Make sure holding brake open time and holding brake operation time are correct for your servomotor.  
 3 A 24 VDC power supply is to be provided by customers.

## Ratings and Specifications

### ● Allowable Load Moment of Inertia at the Motor Shaft

The rotor moment of inertia ratio is the value for a servomotor without a gear and a holding brake.

Servomotor Model	Servomotor Rated Output	Allowable Load Moment of Inertia (Rotor Moment of Inertia Ratio)
SGMSV-10 to -70	1.0 to 7.0 kW	5 times

### ● Load Moment of Inertia

The larger the load moment of inertia, the worse the movement response.

The allowable load moment of inertia ( $J_L$ ) depends on motor capacity, as shown above. This value is provided strictly as a guideline and results may vary depending on servomotor drive conditions.

Use the AC servo drive capacity selection program SigmaJunmaSize+ to check the operation conditions.

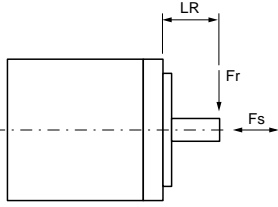
The program can be downloaded for free from our web site (<http://www.e-mechatronics.com/>).

An overvoltage alarm (A.400) is likely to occur during deceleration if the load moment of inertia exceeds the allowable load moment of inertia. SERVOPACKs with a built-in regenerative resistor may generate a regenerative overload alarm (A.320). Take one of the following steps if this occurs.

- Reduce the torque limit.
- Reduce the deceleration rate.
- Reduce the maximum speed.
- Install an external regenerative resistor if the alarm cannot be cleared using the steps above. Refer to Regenerative Resistors on page 386.

### ● Allowable Radial and Thrust Loads

Design the mechanical system so thrust and radial loads applied to the servomotor shaft end during operation fall within the ranges shown in the table.

Servomotor Model		Allowable Radial Load ( $F_r$ ) N	Allowable Thrust Load ( $F_s$ ) N	LR mm	Reference Diagram
SGMSV-	10□□A21	686	196	45	
	15□□A21				
	20□□A21				
	25□□A21	980	392	63	
	30□□A21				
	40□□A21	1176	392	63	
	50□□A21				
70□□A21					